ZMP for the Darwin-OP

Bharadwaj Ramesh

Zero Moment Point

The reaction point of the resultant of all forces and moments due to robots movement must lie within the robots Support polygon





• The position of ZMP is determined based on the following formula :

$$x_{zmp} = x_{com} - (Z_c/g)^*(x_{com})$$
$$y_{zmp} = y_{com} - (Z_c/g)^*(y_{com})$$

Where,

- $x_{zmp} position of zmp in x axis$
- $Y_{zmp} position of zmp in y azis$
- X_{com} position of COM in x axis
- $Y_{com} position of COM in y axis$
- Z_c is the distance of the COM from the ground in the Z axis
- g force due to gravity.

Additional : Calculations for COM

